Performance regression and algorithm selection for MIP-based Neural Network Verification

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Introduction

- Neural Network Verification using a parallel portfolio of solver configurations
- Reduces number of timeouts and improves verification speed
- Further improvements to performance are possible.
- Two main goals:
 - Predicting performance (runtime) of the configurations (with the use of problem-specific instance features)
 - Implementing per-instance algorithm selection techniques to this problem



Source: König, M., Hoos, H.H. & Rijn, J.N.v. Speeding up neural network robustness verification via algorithm configuration and an optimised mixed integer linear programming solver portfolio

Predicting performance of configurations

• Configurations have different solve times, some even timeout

• Can we predict performance?

Config	Solve time	Status
1	2456.4	Infeasible/Unbounded
2	2176.09	Infeasible
3	3692.77	Infeasible
default	9600	User limit

Example of a single sample of the output of the MIPverify solver configurations (sample 17).

Finding features for MIP based problems

• Work already exists for MIP instance features

 But there are other ways to find features for this problem

Problem Type (trivial):

1. Problem type: LP, MILP, FIXEDMILP, QP, MIQP, FIXEDMIQP, MIQP, QCP, or MIQCP, as attributed by CPLEX

Problem Size Features (trivial):

- 2–3. Number of variables and constraints: denoted n and m, respectively
- 4. Number of non-zero entries in the linear constraint matrix, A
- 5–6. Quadratic variables and constraints: number of variables with quadratic constraints and number of quadratic constraints 7. Number of non-zero entries in the quadratic constraint matrix, Q
- 8-12. Number of variables of type: Boolean, integer, continuous, semi-continuous, semi-integer
- 13-17. Fraction of variables of type (summing to 1): Boolean, integer, continuous, semi-continuous, semi-integer
- 18–19. Number and fraction of non-continuous variables (counting Boolean, integer, semi-continuous, and semi-integer variables)
- 20-21. Number and fraction of unbounded non-continuous variables: fraction of non-continuous variables that has infinite lower or upper bound
- 22-25. Support size: mean, median, vc, q90/10 for vector composed of the following values for bounded variables: domain size for binary/integer, 2 for semi-continuous, 1+domain size for semiinteger variables.

Variable-Constraint Graph Features (cheap): each feature is replicated three times, for $X \in \{C, NC, V\}$

- 26–37. Variable node degree statistics: characteristics of vector $(\sum_{c_i \in C} \mathbb{I}(A_{i,j} \neq 0))_{x_i \in X}$: mean, median, vc, q90/10
- 38–49. Constraint node degree statistics: characteristics of vector $(\sum_{x_i \in X} \mathbb{I}(A_{i,j} \neq 0))_{c_j \in C}$: mean, median, vc, q90/10

Linear Constraint Matrix Features (cheap): each feature is replicated three times, for $X \in \{C, NC, V\}$

- 50-55. Variable coefficient statistics: characteristics of vector $(\sum_{c_i \in C} A_{i,j})_{x_i \in X}$: mean, vc
- 56-61. Constraint coefficient statistics: characteristics of vector $(\sum_{x_i \in X} A_{i,j})_{c_i \in C}$: mean, vc
- 62–67. Distribution of normalized constraint matrix entries, $A_{i,j}/b_i$: mean and vc (only of elements where $b_i \neq 0$)

Fig. 2. MIP instance features; for the variable-constraint graph, linear constraint matrix, and objective function features, each feature is computed with respect to three subsets of variables: continuous, C, non-continuous, NC, and all, V. Features introduced for the first time are marked with *.

Source: Frank Hutter, Lin Xu, Holger H. Hoos, Kevin Leyton-Brown, Algorithm runtime prediction: Methods & evaluation, Artificial Intelligence

68–73. Variation coefficient of normalized absolute non-zero entries per row (the normalization is by dividing by sum of the row's absolute values): mean, vc

Objective Function Features (cheap): each feature is replicated three times, for $X \in \{C, NC, V\}$

- 74–79. Absolute objective function coefficients $\{|c_i|\}_{i=1}^n$: mean and stddev
- 80-85. Normalized absolute objective function coefficients $\{|c_i|/n_i\}_{i=1}^n$, where n_i denotes the number of non-zero entries in column i of A: mean and stddev
- 86-91. squareroot-normalized absolute objective function coefficients $||c_i|/\sqrt{n_i}|_{i=1}^n$: mean and stddev

LP-Based Features (expensive):

92–94. Integer slack vector: mean, max, L₂ norm 95. Objective function value of LP solution

Right-hand Side Features (trivial):

96–97. Right-hand side for ≤ constraints: mean and stddev 98–99. Right-hand side for = constraints: mean and stddev 100–101. Right-hand side for ≥ constraints: mean and stddev

Presolving Features* (moderate):

- 102-103. CPU times: presolving and relaxation CPU time
- 104-107. Presolving result features: # of constraints, variables, nonzero entries in the constraint matrix, and clique table inequalities after presolving.

Probing Cut Usage Features* (moderate):

108-112. Number of specific cuts: clique cuts, Gomory fractional cuts, mixed integer rounding cuts, implied bound cuts, flow cuts

Probing Result features* (moderate):

113-116. Performance progress: MIP gap achieved, # new incumbent found by primal heuristics, # of feasible solutions found, # of solutions or incumbents found

Timing Features*

117–121. CPU time required for feature computation: one feature for each of 5 groups of features (see text for details)

Per-instance algorithm selection



Source: J.R. Rice, The Algorithm Selection Problem, 1976.

Going forward...

- 1. Make an overview of the current literature on:
 - MIP solvers
 - Problem specific instance features
 - Algorithm selection methods
 - Etc..
- 2. Replicating results from relevant papers to the problem
- 3. My own implementation
 - Building model to predict runtime using found features
 - Algorithm selection